

# **RATIONAL FREQUENCY SYNTHESIZER EMPLOYING DIGITAL COMMUTATORS**

## **BACKGROUND OF THE INVENTION**

5 It is often required to synthesize a signal source having a frequency which is a rational factor  $n/m$  times an existing reference or clock frequency. This need for synthesis may include cases where  $n$  and  $m$  are relatively prime large integers and typical implementation of such synthesizers involves the use of phase locked loops ("PLL") operating on prescaled (divided) frequency versions of the desired signal and the  
10 reference or clock signal. These PLL synthesizers typically use a comparison frequency that is  $m$  times smaller than the reference or clock signal and thus produce synthesized signals on the desired frequency but with phase noise limitations due to large frequency divisions associated with large values of  $m$ . In such applications, the phase noise power is proportional to the square of the division ratio.

15 It is the object of the instant invention to provide for a synthesizer that permits rational synthesis, i.e. synthesis of a signal source having a frequency which is a rational factor  $n/m$  times an existing reference or clock frequency, without incurring phase noise degradations thereby providing for a signal source with phase noise essentially equal to  
20 that of the reference signal.

## **SUMMARY OF THE INVENTION**

Briefly stated, in accordance with embodiments of the present invention, a method for signal synthesis and a signal synthesizer are provided. A plurality of signals is  
25 generated, e.g. N signals, where N is an integer. The signals each have spectral energy at a frequency  $f_1$ . The signals are applied to an N-way commutator that has M commutator sliders, where M is at least 2 and not greater than N. The commutator slides are rotated across the N inputs of the N-way commutator at a frequency  $f_2$ . At each of the M commutator sliders outputs signs are provided having spectral energy at a frequency  $f_0$ ,  
30 where frequency  $f_0 = f_1 \pm f_2$ . In further forms, particular values of N and M may be

selected to provide particular benefits. A weighting function may be used to improve the purity of  $f_0$ . The signal synthesizer may also be utilized to provide a phase locked loop signal synthesizer or an injection locked oscillator. A new phase locked loop is also provided. This Summary is illustrative and not exhaustive, and is not intended to limit  
5 the scope of the present invention.

### **BRIEF DESCRIPTION OF THE DRAWINGS**

FIG. 1 illustrates a periodic pattern binary signal generator feeding a commutator in accordance with the present invention;

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FIG. 2 shows an example of the periodic binary signals generated by the periodic pattern binary signal generator of FIG. 1;

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FIG. 3 depicts the phase trajectory of the output signal  $f(t)$  as seen on the slider of the commutator of FIG. 1;

FIG. 4 illustrates schematically the Fourier spectrum of the output signal  $f(t)$  in FIG. 1;

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FIG. 5 shows an example of two cascaded commutator cells in accordance with the present invention;

FIG. 6 illustrates two cascaded commutator cells followed by a weighting filter in accordance with the present invention;

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FIG. 7 details the implementation of a 4-way commutator as used in the present invention; and

FIG. 8 shows a phase locked loop using a ternary reference signal produced by a commutator cell according to the present invention.

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## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

Figure 1 shows the first element of the preferred embodiment. A Periodic Pattern Generator 10 provides a plurality of periodic signals  $g_0, g_1$  through  $g_{N-1}$   $[[g_N]]$  where  $N$  is the number of output signals from the Periodic Pattern Generator. In the embodiment of Figure 1, a circulating shift register 12 is used to generate these signals. A “shift” signal on line 15 appears at a rate  $q$  times lower than the clock (reference) signal on line 16. Initializing the content of Shift Register 12 is accomplished by means of the Initializer Logic Control unit 11 by loading a digital bit pattern through parallel lines 14 upon the “Load” command on line 13. An alternative Periodic Pattern Generator may be constructed using other means known in the art such as counters and decoders or periodic state machines having multiple taps. In an exemplary exemplary embodiment of the present invention using shift register 12, a square wave pattern is initially loaded (in this case three consecutive “1’s” and three consecutive “0’s”) although, as will be subsequently discussed, other patterns may be advantageous for certain spectral purity requirements. For the square waveform circulating in shift register 12, the resulting waveforms of the periodic signals  $g_0, g_1$  through  $g_{N-1}$   $[[g_N]]$  are shown in Figure 2. As can be seen, these are phase shifted versions of a square wave having a period of  $N*q$  times that of the reference clock signal. We refer to the frequency associated with this period as the ‘shift register frequency’ or the ‘periodic state machine frequency’ which in this case is  $f_c / (Nq)$ , where  $f_c$  is the reference clock frequency. The periodic signals  $g_0, g_1$  through  $g_{N-1}$   $[[g_N]]$  are fed to a Phase Commutator 20, which is an  $N$  way digital multiplexer that is controlled by MUX control lines 22 and provides an output digital signal  $f(t)$  on line 21. The periodic operation of the Phase Commutator 20 is governed by the decoded state of counter 24. Upon each clock cycle, decoder 23 decodes a different state of counter 24 and thus controls the commutator’s slider to select a different signal  $g_j$  to be connected to the output line 21. If every signal line from  $g_0, g_1$  through  $g_{N-1}$   $[[g_N]]$  is selected sequentially in order, the period of the Phase Commutator 20 can be as low as  $N$  times that of the reference. If one includes in the drive of counter 24 an internal pre-divider of the reference clock by an integer  $p$ , then the Commutator 20 frequency is  $N*p$

times lower than that of the reference clock signal. We call this frequency the  
 'commutator frequency' which is given by  $f_c / (N q)$ . Because the periodic signal's  
 phase available to the slider of the Commutator **20** is advancing through the sequential  
 selection of signals  $g_0, g_1$  through  $g_{N-1} [[g_N]]$ , one can regard the Phase Commutator's  
 5 action as providing at its output a signal  $f(t)$  with a phase which is a discrete-time step  
 approximation to a continuous linear phase shift with time. This is shown in Figure 3 for  
 a case in which  $N=6$ . In reference to Figure 3, the phase trajectory of the signal  $f(t)$  is  
 depicted as a step trajectory **30**, having six equal phase steps per cycle of the Phase  
 Commutator. It can be seen that it is a discrete time approximation to the linear phase  
 10 trajectory **31** shown as a straight broken line.

Those skilled in the art of signal parameters would now appreciate that a signal  
 undergoing a linear phase shift with time is simply a signal whose original frequency is  
 translated or changed. The amount of frequency shift is simply given by the slope of the  
 15 phase trajectory and is equal to the inverse of the time period over which a total phase  
 shift of  $2\pi$  takes place. In the example of Figure 3, this frequency shift is equal to the  
 commutator's rotation frequency, which is one sixths of the clock frequency. It can be  
 appreciated that in the above example, the phase shift steps are positive, meaning that the  
 frequency shift is positive, resulting with a higher signal frequency. By reversing the  
 20 Phase Commutator **20**'s slider ~~rotation~~ rotation direction to the opposite direction  
 (clockwise), the phase trajectory as in Figure 3 assumes a negative slope, corresponding  
 to a negative frequency shift. An equivalent frequency decrement effect can be achieved  
 by keeping the Phase Commutator **20** operating in its original direction but reversing the  
 bit shift direction for shift register **12**. In either case, the relative direction of phase shift  
 25 determines whether the frequency shift (or frequency conversion) is upwards or  
 downwards. This frequency conversion effect is equivalent to frequency mixing known in  
 the art, and as such, the upward conversion and downward conversion is equivalent to  
 Single Side Band (SSB) mixing with resultant Upper Side Band (USB) and Lower Side  
 Band (LSB) mixing components respectively.

In another mode of the preferred embodiment of the instant invention, the slider of Phase Commutator **20** may be advanced by  $k$  signal lines per each clock cycle rather than one, thereby providing the output sequence  $g_0, g_k, g_{2k}, g_{3k}$  where the subscript index is valued modulo  $N$ . This is shown for example in Figure 3 by phase trajectory **32**, which  
 5 now approximates a continuous linear phase shift trajectory **33**. As can be seen in this example the resultant phase slope is doubled, meaning that the conversion frequency shift is twice that related to trajectory **30**. In this case there are only three phase sampling points per cycle, which degrades the quality of the approximation of a linear phase shift trajectory. However, as long as there are more than two phase samples per cycle (Nyquist  
 10 Sampling Criterion), a significant energy at the intended shifted frequency will be present within the output signal  $f(t)$ . However the spectral purity will be poorer than that which results from a Phase Commutator having a larger number ( $N$ ) of phase shifted signal lines.

A qualitative depiction of the amplitude spectrum of the output signal  $f(t)$  as a function of frequency is shown in Figure 4. The intended frequency of the output signal is shown to possess a spectral component **40**, having a dominant energy component in comparison to all other components. The commutator frequency **40** is shown on a frequency scale that is centered about it for discussion purposes. The frequency scale uses integral units of the  
 20 shift register frequency **42**. The spectral components **43, 44, 45** and **46** are due to the odd harmonic content of the square wave nature of the signals  $g_j$  provided by the Periodic Pattern Generator **10**, and are related respectively to the 3<sup>rd</sup>, 5<sup>th</sup> and 7<sup>th</sup> harmonics of the square wave provided by the Periodic Pattern Generator **10**. Note that other lower level spectral components **47** may be present. It can be shown mathematically that the relative  
 25 levels of spectral components **47** are related to the resolution of phase increments (to the value of  $N$ ) and to the relative congruence of the commutator frequency and the shift register frequency. For commutator frequencies sufficiently high compared to that of the shift register cycle, components **47** can be made progressively small with the increasing values of  $N$ . This is due to the fact that as  $N$  increases (keeping the commutator and shift  
 30 register frequencies constant), the phase trajectories **30** of Figure 3 asymptotically

approach the continuous linear phase trajectory **31**. Of course, higher values of  $N$  would require faster clock frequencies for obtaining the same frequency at the output of the Phase Commutator. Moreover, it will be appreciated that the increase in  $N$  would also necessitate higher complexity in implementing the Periodic Pattern Generator **10** and the  
 5 Phase Commutator **20**.

Turning back to the resultant frequency of the output signal, based on the foregoing discussion, it should be understood that the dominant desired frequency component due to the frequency conversion is shifted by an amount equal to  $f_c k s / (N q)$  with a sign  
 10 dependent on the rotation direction of the commutator and where we designate the rotation direction by the sideband value  $s$  assuming values of  $+1$  or  $-1$ . By cascading several commutators of order  $N$  driven for different rotation rates, one can obtain a signal with resultant frequency  $R_o$  given by

$$15 \quad (1) \quad R_o = \frac{f_c}{N} \left( \frac{k_1 s_1}{q_1} + \frac{k_2 s_2}{q_2} + \dots \right)$$

where numeric subscripts indicate the commutator cell index. This sum expression is due to the cascaded mixing nature of the commutators. Thus, signals whose frequencies constitute a rich set of possible rational values for  $R_o/f_c$  can be generated with these structures – imparting the term Rational Synthesizer to the embodiments as described.

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For a synthesizer of the present invention employing low complexity commutators (low values of  $N$ ), the only practical value of  $k$  may be 1. Thus, given a desirable synthesis ratio  $R_o/f_c$ , the problem at hand is to find values of  $q_1, q_2, \dots$ , so that  $NR_o/f_c = 1/q_1 \pm 1/q_2 \pm \dots$  holds. In other words, one needs to represent the desirable  
 25 synthesis ratio (assumed to be a rational number) as a sum of unit fractions. In order to minimize complexity, it is desirable to find such unit fraction representations with a minimum number of terms and preferably with the smallest possible values for the denominators  $q_1, q_2, \dots$ . The number theory literature provides several algorithms for arriving at such representations with a substantial number of works on the ‘Egyptian

Fractions' case, for which all fractions are positive. A short survey of such mathematical works is given in section D11 (starting at page 158) of Richard K. Guy's book entitled *"Unsolved Problems in Number Theory"*, Second Edition (1994), published by Springer-Verlag. It should be appreciated that allowing for both negative and positive unit fractions in the representation of the synthesis ratio minimizes the mathematical constraints, which can result in shorter sums with smaller denominators. In this general case, those skilled in the mathematical art of number theory would appreciate that it is useful to employ the simple property of the continued fraction representation of a rational number  $R$  given by :

$$R = a_0 + \frac{1}{a_1 + \frac{1}{a_2 + \frac{1}{a_3 + \frac{1}{a_4 + \frac{1}{a_5 + \dots}}}}}$$

wherein  $a_i$  are integers. Because  $R$  is rational, the continued fraction is finite. The *convergents* of  $R$  are formed by truncating the sequence and their values are alternately above and below  $R$ , and are successively better rational approximations to  $R$ . Successive convergents have differences that are unit fractions with increasing denominators. The sequence of these differences gives a desired unit fraction representation of  $R$  with alternating signs. Often, several consecutive terms in this sequence can be combined to form a single unit fraction with a smaller denominator, yielding a shorter sequence. For practical values of  $R$  it is possible to find a unit fraction representation with only three terms. This property was suggested by Schinzel's modification of Erdős' conjecture on unit fractions as described in an article by W. Sierpinski, *"Sur les decompositions de nombres rationals en fractions primaires"* Mathesis, 65; pp 16-32, (1956). Hence, theoretically, it should be possible to implement the Rational Synthesizer of the current invention with a cascade of only two commutator cells.

The Phase Commutator shown in Figure 1 has only one output. In order to provide for cascading of commutators and in order to obtain best spectral purity results, it would be advantageous to have a commutator with multiple sliders that commute sequentially over the input signals  $g_0, g_1$  through  $g_{N-1}$   $[[g_N]]$  and consequently provide a sequence of output signals  $f_0, f_1$  through  $f_{N-1}$   $[[f_N]]$  all having similar spectral characteristics but with different phases. In that way, cascading that well preserves the phase sampling integrity can be made possible. An example of a rational synthesizer in accordance with the present invention that uses cascaded commutators is shown in Figure 5. In this example, Commutator Cell 2 has three inputs ( $N = 3$ ) on lines 52 and three outputs on lines 53. It is cascading Commutator Cell 1, which is a subsampled  $N = 6$  commutator running on its own independent counter. In figure 6, a cascade of two independent four way commutators ( $N = 4$ ) is shown. The first commutator cell 61 is fed by the 4 phase periodic generator 60. The output signals of the first cell feeds the second commutator cell 62. It is understood that each commutator cell has within it the specific counters and decoders required for the appropriate frequencies. The four phase outputs of the second commutator cell 62 is feeding the weighting filter 63 which can be used to further filter out certain undesirable spectral components. The filter's operation is similar to a Finite Impulse Response (FIR) filter as it enables the use of various weighting coefficients for each of the output phases, permitting the construction of an output signal that is a linear combination of all output signals. These coefficients are determined by the values of the input resistors to the differential amplifier of the weighting filter. If further spectral purification of undesired sidebands is required it can be achieved by feeding the output signal of weighting filter 63 to an Injection Locked Oscillator (ILO) or Phase Locked Loop (PLL) shown as item 64. That way, the output signal on line 65 can be free of spurious components.

There is considerable advantage in using four way commutators since they provide a good compromise of phase sampling resolution and implementation complexity while maintaining appreciable frequency of operation. This is because of very efficient designs available for four way digital multiplexers. Detailed description of embodiments and



applications using the four way commutator-based rational synthesizers of the present invention are provided in a copending application entitled "Rational Frequency Synthesizers" filed on May 25, 2000 for the benefit of a common assignee, which is incorporated herein by this reference in its entirety. According to the present invention,

5 an example of a full four-way commutator with four inputs  $I_1$ ,  $I_2$ ,  $I_3$  and  $I_4$  and having four outputs  $O_1$ ,  $O_2$ ,  $O_3$  and  $O_4$ , is shown in Figure 7. The decoder (not shown) commands the operation of the commutator via control lines C1 through C4 in order to effect the proper sequential routing of the commutator. The four sequential states that are cycled through by proper control line values of 1 or 0 for C1 through C4 are shown in the following

10 table, wherein the sense of control lines C1 through C4 is such that their logical values are all 0 at their state shown in Figure 7.

<u>State</u>	<u>C1=C2</u>	<u>C3</u>	<u>C4</u>	<u>O<sub>1</sub> Output connected to:</u>	<u>O<sub>2</sub> Output connected to:</u>	<u>O<sub>3</sub> Output connected to:</u>	<u>O<sub>4</sub> Output connected to:</u>
<u>0</u>	<u>0</u>	<u>0</u>	<u>0</u>	<u>I<sub>1</sub></u>	<u>I<sub>2</sub></u>	<u>I<sub>3</sub></u>	<u>I<sub>4</sub></u>
<u>1</u>	<u>1</u>	<u>0</u>	<u>1</u>	<u>I<sub>2</sub></u>	<u>I<sub>3</sub></u>	<u>I<sub>4</sub></u>	<u>I<sub>1</sub></u>
<u>2</u>	<u>0</u>	<u>1</u>	<u>1</u>	<u>I<sub>3</sub></u>	<u>I<sub>4</sub></u>	<u>I<sub>1</sub></u>	<u>I<sub>2</sub></u>
<u>3</u>	<u>1</u>	<u>1</u>	<u>0</u>	<u>I<sub>4</sub></u>	<u>I<sub>1</sub></u>	<u>I<sub>2</sub></u>	<u>I<sub>3</sub></u>

15 In reference to Figure 1, it is evident that a full cycle of the state machine is completed every  $qN$  clock pulses over a duration which is the fundamental period. During that period, the commutator completes  $q$  revolutions, giving rise to a dimensionless commutator frequency  $q$ . The single cell structure of Figure 1 having instead  $N$  commutator sliders, each with a corresponding output signal, can be more generally

20 analyzed mathematically by using the isomorphism between the field of binary values 1 and 0 and the binary number field of +1 and -1. Thus, without loss of generality, all binary signals assume values of +1 or -1.

Generally, for an  $N$  way rational synthesizer commutator we designate the  $m^{\text{th}}$  output signal from a commutator as a function of time by  $f_m(t)$  and we note that it is periodic and thus can be represented by its Fourier spectral components which we designate as  $F_m(n)$ .

Here,  $n$  is the harmonic index of the frequency which is  $n$  times the frequency of the

5 fundamental period. The input signals to the commutator as functions of time are designated as  $g_0(t)$ ,  $g_1(t)$  through  $g_{N-1}(t)$  [ $g_M(t)$ ]. If these signals have more generally, not one cycle within the  $N$  stage shift register, but  $r$  complete cycles, it can be shown that the Fourier spectrum of the output signals is given by

$$10 \quad (2) \quad F_m(n) = \frac{rNq}{2\pi(r+sq)} \exp[2\pi ismn / (qN)] \sum_{l=-\infty}^{\infty} \left[ \frac{G(l) \exp[-2\pi ismrl / (qN)]}{rl - n} \right] H(l)$$

where  $H(l)$  is an indicator function of  $l$  given by

$$(3) \quad H(l) = \begin{cases} 1 & \text{whenever } l(sr+q) - sn = qNu ; \text{ where } u \text{ is an integer} \\ 0 & \text{otherwise} \end{cases}$$

15 and where  $G(l)$  is the Fourier coefficient at frequency  $l$  of the periodic signal  $g_0(t)$ . By inspecting Equation (3) one notes that nonzero Fourier coefficients will only be at (positive or negative) frequencies  $n$  for which the linear Diophantine equation in integers  $l$  and  $u$  at the top part of the definition of  $H(l)$ , has solutions. Using basic number  
20 theoretic tools one finds that for a square wave form of  $g_0(t)$  (having only odd order harmonics  $l$ ) the offset frequencies  $n$  for which there is nonzero power is given by

$$(4) \quad n = \mu d + sq + r ; \text{ where } d \text{ is the greatest common divisor denominator of } 2(sr+q) \text{ and } qN$$

Here  $\mu$  is any positive or negative integer used to designate the non-zero spectral

25 component. It is therefore possible to choose the parameters that, on the one hand, the desired frequency is generated and on the other hand, such that  $d$  is maximized, providing maximum spectral purity clearance about the desired frequency  $sq+r$ .

The expressions for the spectral components in Equations 2-4 above are for periodic pattern generators that cycle through a square wave which contains all odd harmonics. These components and their frequency aliases mix with the commutator frequencies and  
5 in some instances can produce undesirable sideband components near the desirable frequency. It is possible to construct a signal pattern that is free from all harmonics up to 5<sup>th</sup> order by the periodic pattern generator shown in Figure 8, which shows an embodiment of the rational synthesizer with a PLL using six way commutator with a non-square wave pattern, resulting in ternary level representation over the two slider output  
10 signals designed specifically to offer better spectral purity. It also incorporates a differential DSB mixer for applications requiring high frequency mixing and further incorporates a differential phase detector (PD) which permits the propagation of the symmetry and the ternary value into the differential low pass filter 86. In this case, VCO 88 is locked on a frequency that is an integral multiple of the desired frequency of the  
15 Rational Synthesizer at outputs 82 and 83.